

RESEARCH LABORATORY HUMAN COMPUTER INTERACTION

Research profile

Human Computer Interaction and Computer Vision

Competences / Infrastructure

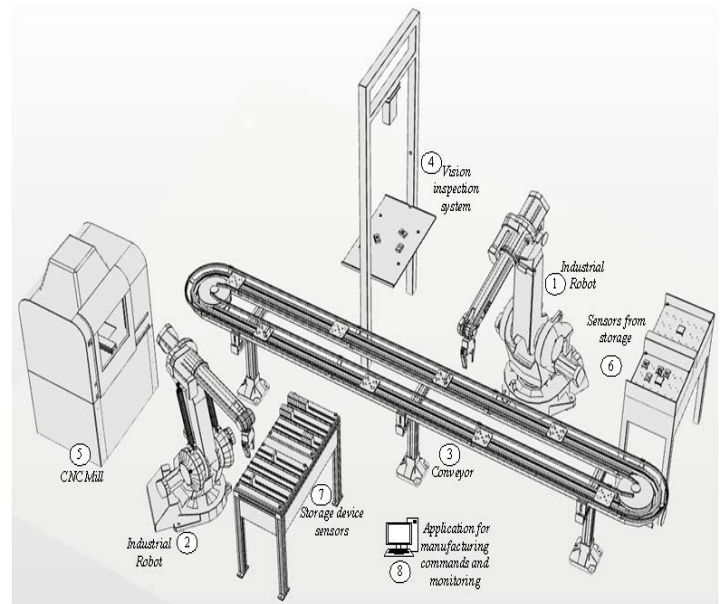
Computers and Laptops (Intel 7, 8- 16 GB RAM), 4 hamlets EPOC Emotive for BCI, 6 Leap Motion Devices, Remote Eye Trackers, Glasses Vuzix for Eyetracking, Kinetics V1 and V2, Bracelets for EMG, Oculus Rift, Texas instruments DRV2603 Vibration Kit, Myo gesture Control Armband, Triple source HM 8040-3, Function Generator HM 8030-6, P Samsung SNH-E6411 Video Cam; IMU Sensors, Kinect V2, haptic devices.

Coordinators:

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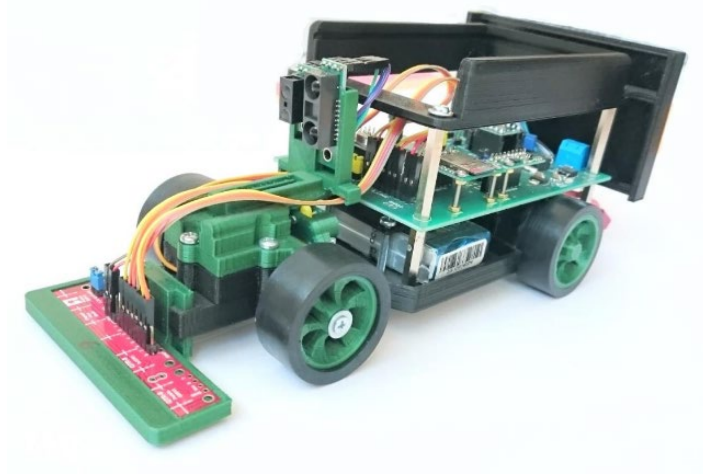
RESEARCH LABORATORY

LoRIS - Laboratory of Robotics and Intelligent Systems

Research profile | Robotics and Intelligent Systems

Competences / Infrastructure | *Mobile robot platform* with: 2 Khepera III mobile robots, Lego Mindstorms EV3 kits, Crazyflie 2.0 quadcopters, computers;
Flexible manufacturing cell with: ABB IRB 1400 robotic arm, ABB IRB 2400L, Fanuc M6iB/2HS, RIP 0.2, grippers SCHUNK DPG 100/1 and SMC MHZ2-20D, machine tool EMCO CNC PC Mill 55, FlexLink conveyor.

Coordinators:	Prof. dr. eng. Kloetzer Marius, kmarius@ac.tuiasi.ro Assoc. prof. dr. eng. Burlacu Adrian, aburlacu@ac.tuiasi.ro Assist. prof. dr. eng. Panescu Doru-Adrian, dorup@ac.tuiasi.ro Assist. prof. dr. eng. Pascal Carlos, cpascal@ac.tuiasi.ro Assist. prof. dr. eng. Cristina Budaciu, cbudaciu@ac.tuiasi.ro
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RESEARCH LABORATORY

Automated vehicles

Research profile

Automated vehicles platooning

Competences / Infrastructure

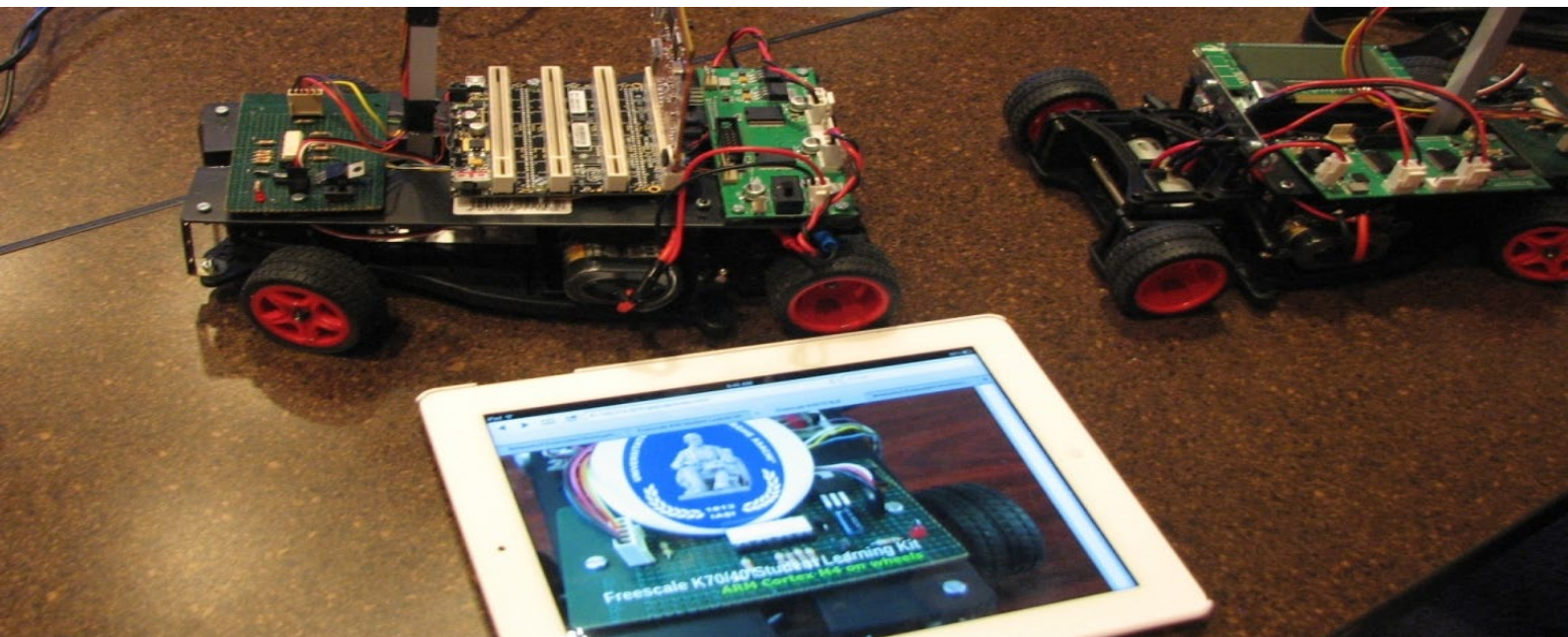
10 Prototype model cars with: 16bit dsPIC33FJ128MC802 microcontroller, 32bit microcontroller on a STM32F3DISCOVERY board, DC and servo-motors, various sensors, nRF24L01 based RF module; Balance charger (X-Peak 50 Bal) for Li batteries, 4 Balance chargers for LiPo batteries, digital multimeter Keysight Technologies U1232a, 10 PICkit3 In-Circuit Debuggers/Programmers

Coordinators:

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RESEARCH LABORATORY MACHINE LEARNING AND INTERNET OF THINGS

Research profile | Internet of things, machine learning, sensors networks, trusted embedded computers

Competences / Infrastructure | Local Area Network (10), Linux Computers(1-4 core)(10), ARM Cortex M3/4 Development Board (20), ARM cortex M0 Development Board (20), Oscilloscope (1), image sensors, BLDC Motors,DC motors, stepper motors, Bluetooths Modules, Quadcopter educational/research prototype, e_car research prototype, applications platforms for Internet of Things, Open Educational Resource site - www.embedac.ro .

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RESEARCH LABORATORY COMPUTER ARCHITECTURE AND EMBEDDED SYSTEMS

Research profile

Computer architecture, embedded systems, intelligent systems, cyber-physical systems, digital signal processing, wireless sensor networks, low power solutions, reconfigurable computing, industrial gas/oil automation system design

Competences / Infrastructure

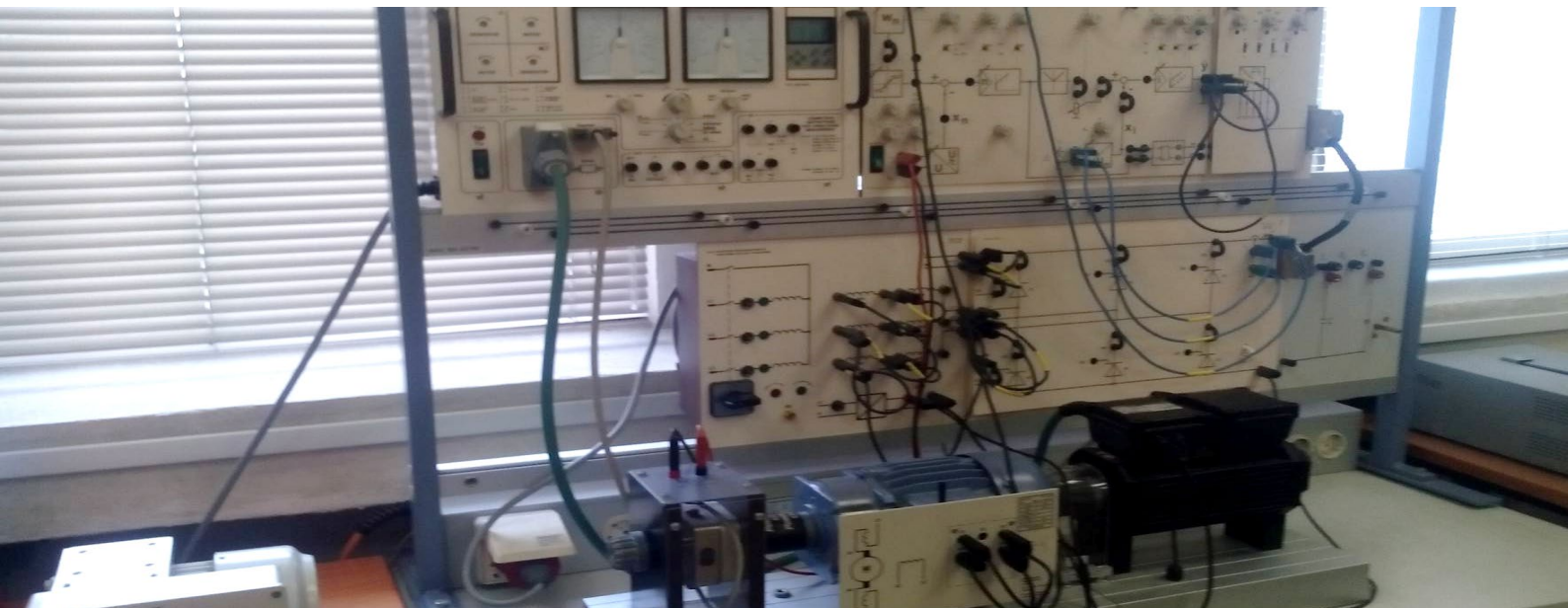
- Local Area Network with 12 student workstations and 6 research workstations
- Development boards/systems: AVR ATmega (20), Microchip DSPIC (15), ARM Cortex M3/M4 (20), Xilinx FPGA ZedBoard (2), Xilinx FPGA Arty (11), Blackfin Processors (2), PowerPC processors(5), Renesas RX Development Platforms (6)
- Tools: JBC rework station, DSO Oscilloscopes (2 x Tektronics, 1 x LeCroy), Power sources (15 x Hameg), Signal/function generators (1 x Tektronics, 6 x Hameg), Counters (6 x Hameg), Multimeters (6 x Hameg, 5 x Fluke, 1 x PICOTEST), PCB CNC LPKF Protomat M60

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RESEARCH LABORATORY CONTROL SYSTEMS AND FAULT DIAGNOSIS

Research profile

- Control structures and algorithms
- Embedded systems design and applications
- Electrical drives design and control
- Industrial control systems design
- Identification and fault diagnosis

Competences / Infrastructure

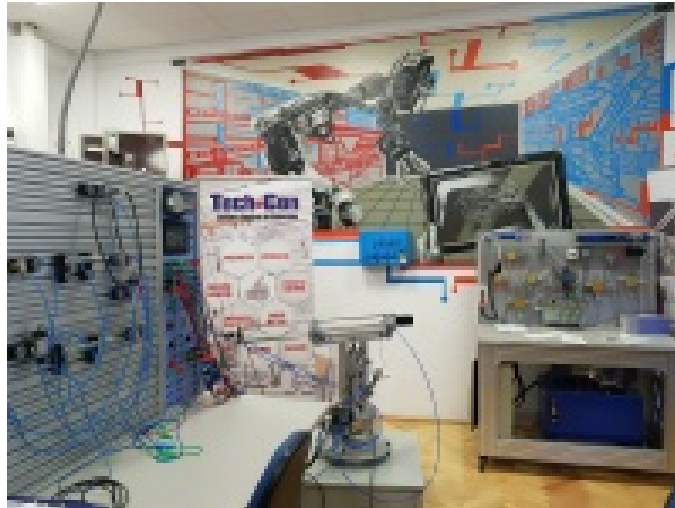
AC drive control systems, DC drives control systems, Test bench for electric drives speed control, dSPACE controller boards with software packages, FPGA platforms Xilinx Spartan 3E, LPKF Protomat C60 – PCB rapid prototyping, Universal Programmer/Tester - Labprog+, Test and measurement equipment, desktop computers

Coordinators:

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RESEARCH LABORATORY

Industrial Control Technology (Tech-Con Lab)

Research profile | Electric, hydraulic, pneumatic and vacuum drives, Automatic control, Sensors and Transducers, Mechatronic system & Autonomous mobile robot, Modelling and simulation of processes, Industry 4.0

Competences / Infrastructure

- Omnidirectional mobile robot - DIDAND platform
- Pneumatical, Hydraulical and Vacuum drives stand
- Conveyor system, Twin rotor for mimo system
- Siemens equipment for process control (PLCs, HMIs, Servo drive, AC drive, Simocode, mobile wireless antenna, RFID, Siwarex, Energy meter, Stabilized power supply)
- Sensors and transducers (temperature, flow, pressure, distance, proximity, safety)
- Test and measurement equipment (NI SC-2345 Signal Conditioning Connector Block with Configurable Connectors, Osciloscop Tektronics TDS3054C, Ditigal Phosphor Oscilloscope, 4 canale, 500Mhz, 5Gs/s, tester for sensors, optical tachometer, digital multimeter Chint)
- Miniature machine tools (Denford Micromill 2000 Milling Machine, Denford Microturn CNC Lathe)

Coordinators: Assist. prof. dr. eng. Constantin Catalin Dosoftoi, cdosoftoi@ac.tuiasi.ro
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